

Conformal Geometry in the Bulk

A Boundary Calculus for Conformally Compact Manifolds

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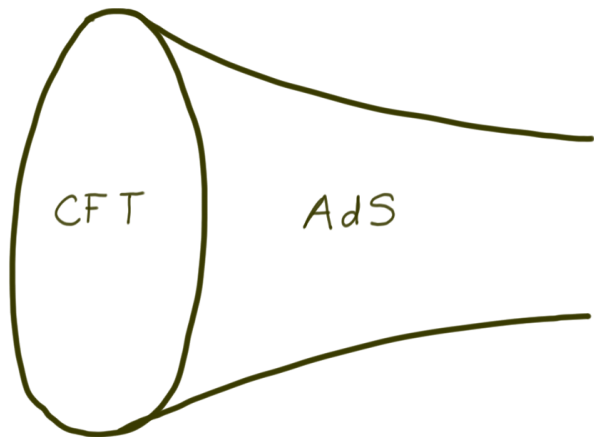
October 3, 2011

arXiv:1104.2991
with Rod Gover

arXiv:1104.4994, 1007.1724, 1003.3855, 0911.2477, 0903.1394, 0812.3364, 0810.2867
with Roberto Bonezzi, Olindo Corradini, Maxim Grigoriev, Emanuele Latini and Abrar Shaikat

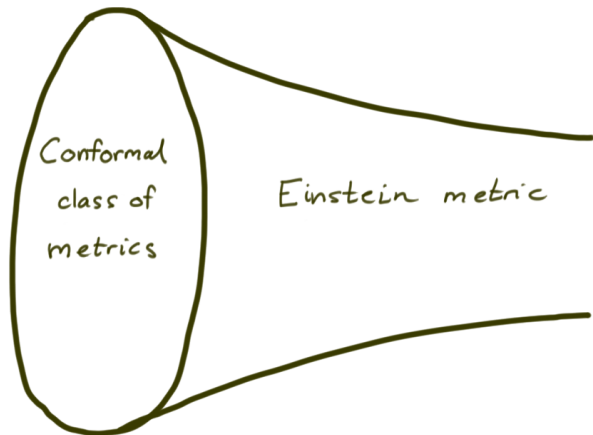
Main Idea

AdS/CFT \Rightarrow



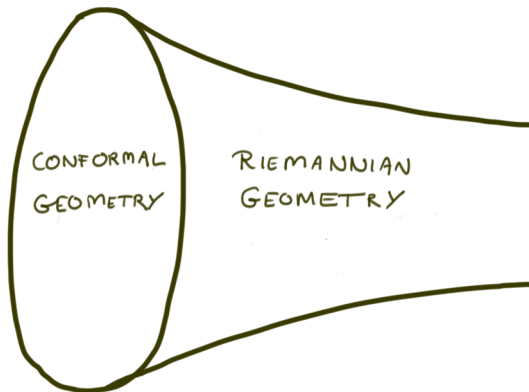
Main Idea

or



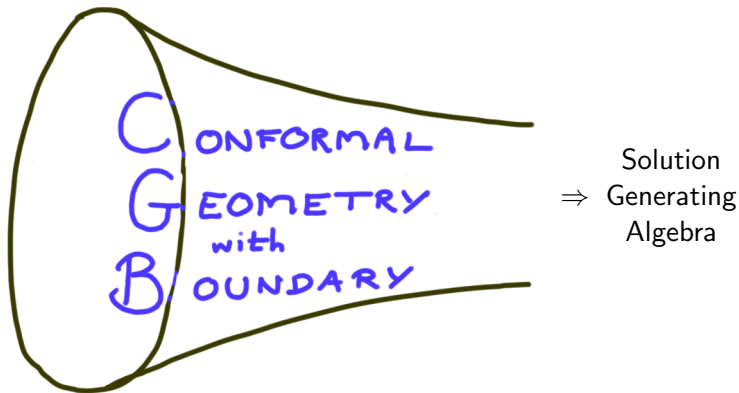
Main Idea

or



Main Idea

better

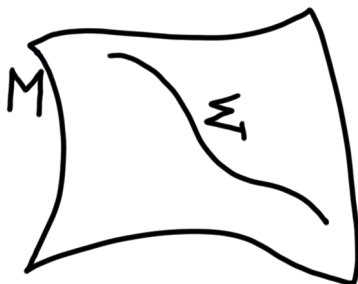


(or “Almost Riemannian Geometry” \diamond)

\diamond A.R. Gover, *Almost conformally Einstein manifolds and obstructions*, in *Diff. Geom. Appl.* 247, Matfyzpress, Prague, 2005.

[arXiv:math/0412393](https://arxiv.org/abs/math/0412393)

Describing the Boundary



$M = \text{bulk}$

$(M, [g]) = \text{conformal manifold}$

$$g_{\mu\nu} \sim \Omega^2(x)g_{\mu\nu}$$

$\Sigma = \text{boundary}$

inherits conformal class of metrics

$$(\Sigma, [g_\Sigma])$$

To say *where* the boundary is introduce an *almost everywhere* positive function $\sigma(x)$.

Σ is the zero locus of σ .

The Scale

Along Σ , the function σ encodes boundary data, in the bulk it is a spacetime varying Planck Mass/ Newton Constant.

- The *scale* $\sigma(x)$ is the gauge field for local choices of units

$$\sigma(x) \sim \Omega(x)\sigma(x)$$

- The double equivalence class $[g_{\mu\nu}, \sigma] = [\Omega^2 g_{\mu\nu}, \Omega\sigma]$ determines a canonical metric g^0 AWAY FROM Σ

$$[g_{\mu\nu}, \sigma] = [g_{\mu\nu}^0, 1]$$

in units $\kappa = 1$.

- Example:** AdS

$$ds_0^2 = \frac{dx^2 + h(x)}{x^2}, \quad \sigma_0 = 1,$$

but along Σ should use

$$ds^2 = dx^2 + h(x), \quad \sigma = x,$$

well defined at the boundary $\Sigma = \{x = 0\}$.

The Normal Tractor

Along Σ , $\nabla\sigma$ encodes the normal vector n and $\nabla \cdot n$ the mean curvature H

Introduce *scale* and *normal* tractors

$$I = \begin{pmatrix} \sigma \\ \nabla\sigma \\ -\frac{1}{d}(\Delta\sigma + \sigma J) \end{pmatrix}, \quad N = \begin{pmatrix} 0 \\ \hat{n} \\ -H \end{pmatrix},$$

$$d := \dim M, \quad R_{\mu\nu\rho\sigma} := W_{\mu\nu\rho\sigma} + (g_{\mu\rho}P_{\nu\sigma} \pm 3 \text{ more}), \quad J := P_{\mu}^{\mu}$$

Theorem (Gover)

$$I^2 = 1 \quad \Rightarrow \quad I|_{\Sigma} = N$$

Away from Σ the scale tractor controls bulk geometry,
along Σ it carries boundary information.

Tractors

Probably not surprising that to describe conformal geometry, one should use 6-vectors rather than 4-vectors! Spacetime remains 4-dimensional.

Weight w *tractors* are defined by their gauge transformation w.r.t. conformal transformations

$$T^M := \begin{pmatrix} T^+ \\ T^m \\ T^- \end{pmatrix} \mapsto \Omega^w \begin{pmatrix} \Omega & 0 & 0 \\ \Upsilon^m & \delta_n^m & 0 \\ -\frac{1}{2\Omega} \Upsilon^2 & -\frac{1}{\Omega} \Upsilon_n & \frac{1}{\Omega} \end{pmatrix} \begin{pmatrix} T^+ \\ T^n \\ T^- \end{pmatrix} =: \Omega^w U^M_N T^N,$$

Here $\Upsilon_\mu := \Omega^{-1} \partial_\mu \Omega$ and $U^M_N \in SO(d, 2)$.

Tractors give a tensor calculus for conformal geometry \diamond .

Example: $T^2 := 2T^+T^- + T^m T_m$ is a conformal invariant

\diamond T.N.Bailey, M.G.Eastwood, A.R.Gover, *Thomas's structure bundle for conformal, projective and related structures*, Rocky Mountain J.Math. 24 (1994) 1191.

Parallel Scale Tractors

The tractor bundle is physically very interesting because parallel tractors correspond precisely to Einstein metrics.

The tractor covariant derivative on weight zero tractors

$$\nabla_{\mu} T^M := \begin{pmatrix} \partial_{\mu} T^+ - T_{\mu} \\ \nabla_{\mu} T^m + P_{\mu}^m T^+ + e_{\mu}^m T^- \\ \partial_{\mu} T^- - P_{\mu}^m T_m \end{pmatrix} \mapsto U^M_N \nabla_{\mu} T^N.$$

Theorem (Sasaki; Bailey, Eastwood, Gover; Nurowski)

$(M, [g])$ conformally Einstein $\Leftrightarrow (M, [g])$ admits a parallel scale tractor.

Proof.

Call $I_M = (\rho, n_m, \sigma)$ and study

$$\nabla_{\mu} I^M = 0 \Leftrightarrow \begin{cases} \partial_{\mu} \sigma - n_{\mu} = 0 \\ \nabla_{\mu} n_{\nu} + P_{\mu\nu} \sigma + g_{\mu\nu} \rho = 0 \\ \partial_{\mu} \rho - P_{\mu\nu} n^{\nu} = 0 \end{cases}$$

□

No physics depends on local choices of unit systems \Rightarrow express any theory in tractors. Unification a lá 3 \rightarrow 4-vectors!

- Einstein–Hilbert action $S[g, \sigma] = \int \frac{\sqrt{-g}}{\sigma^d} I^2$.
- I^M parallel $\Rightarrow I^2 = \text{constant}$; this is the cosmological constant!
- Replace derivatives by Thomas D -operator; unifies Laplacian and gradient!

$$D^M := \begin{pmatrix} w(d + 2w - 2) \\ (d + 2w - 2)\nabla \\ -\Delta - wJ \end{pmatrix}, \quad D^M D_M = 0.$$

- Weights of tractors = masses; Breitenlohner–Freedman bounds for free!

- Wave equations for tractor tensors $I \cdot D T = 0$

- **Example** $T = \varphi$, weight w scalar, $\sigma = 1$,

$$I \cdot D \varphi = - \left[\Delta - \frac{2J}{d} w(d + w - 1) \right] \varphi$$

$$\text{Mass—Weyl-weight relationship } m^2 = -\frac{2J}{d} \left[\left(w + \frac{d-1}{2} \right)^2 - \frac{(d-1)^2}{4} \right].$$

\diamond Gover, Shaikat, AW

Tractor Maxwell Theory

- Maxwell Tractor, V^M , weight w with gauge invariance

$$\delta V^M = D^M \xi = (d + 2w) \begin{pmatrix} (w + 1)\xi \\ \nabla \xi \\ \star \end{pmatrix}$$

- $D_M V^M$ is gauge inert so impose

$$D \cdot V = 0, \quad \text{determines } V^-.$$

- Get gauge transformations of Stückelberg-massive Proca system

$$\delta V^+ = (d + 2w)(w + 1)\xi, \quad V^m = (d + 2w)\nabla^m \xi.$$

- Tractor Maxwell Field Strength

$$F^{MN} = D^M V^N - D^N V^M, \quad \text{gauge invariant.}$$

- Equations of motion by coupling to scale

$$J^N = I_M F^{MN} = 0, \quad \text{Proca Equation}$$

- For $w = -1$, V^+ decouples, get standard **massless** Maxwell.
- For $w = 1 - \frac{d}{2}$, scale tractor **decouples!**
- In four dimensions $1 - \frac{d}{2} = -1$ so this says Maxwell is **Weyl invariant**.
- In $d \neq 4$, get Weyl invariant Deser–Nepomechie theory

$$\Delta A_\mu - \frac{4}{d} \nabla^\nu \nabla_\mu A_\nu + \frac{d-4}{4} \left(2P_{\mu\nu} A^\nu - \frac{d+2}{2} A_\mu \right) = 0.$$

Unify Massive, Massless and Partially Massless Theories

Example

Tractor Gravitons h_{MN} with

$$\delta h_{MN} = D_M \xi_N + D_N \xi_M, \quad D^M h_{MN} - \frac{1}{2} D_N h_M^M = 0,$$

Tractor Christoffels $2\Gamma_{MNR} = D_M h_{NR} + D_N h_{MR} - D_R h_{MN}$

$$G_{MN} = I^R \Gamma_{MNR} = 0, \quad \text{massive gravitons}$$

- Examine gauge transformations

$$\begin{cases} \delta h^{++} = (d + 2w)(w + 1)\xi^+ \\ \delta h^{m+} = (d + 2w)[w\xi^m + \nabla^m \xi^+] \\ \delta h^{mn} = (d + 2w)[\nabla^m \xi^n + \nabla^n \xi^m + \frac{2J}{d}\eta^{mn}\xi^+] \end{cases}$$

- $w = 0$, massless gravitons
- $w = -1$, partially massless gravitons

$$\delta h^{mn} = (d - 2) \left[\nabla^m \nabla^n + \frac{2J}{d} \eta^{mn} \right] \xi^+.$$

Boundary Problems

Problem

Given a boundary tractor T_Σ , find a tractor T on M such that

$$T|_\Sigma = T_\Sigma \quad \text{and} \quad I \cdot D T = 0.$$

In a given Weyl frame, this is a Laplace type problem, so *could* just choose coordinates and study the resulting PDE.

Method

- Boundary data



- Extend T_Σ arbitrarily to T_0 with $T_0|_\Sigma = T_\Sigma$



- Iteratively find $T^{(1)}, T^{(2)}, \dots$ approaching solution T , with $T^{(l)}|_\Sigma = T_\Sigma$



- Check solution T is *independent* of original choice of extension T_0 .

Boundary Calculus

Observe that because $T|_{\Sigma} = T_{\Sigma} = T_0|_{\Sigma}$

$$T = T_0 + \sigma S, \quad \text{for some } S.$$

This suggests to search for an expansion in the scale!

$$T^{(l)} = T_0 + \sigma T_1 + \sigma^2 T_2 + \cdots + \sigma^l T_l.$$

Need algebra of $l \cdot D$ and σ , remarkably

$$[l \cdot D, \sigma] = (d + 2w)l^2$$

Or calling $x := \sigma$, $h := d + 2w$, $y = -\frac{1}{l^2}l \cdot D$ we have the $\mathfrak{sl}(2)$ *solution generating* algebra

$$[x, y] = h, \quad [h, x] = 2x, \quad [h, y] = -2y$$

The Solution

Example

Given weighted tractor $hT = h_0T$ and $T = T_0 + xT_1 + x^2T_2 + \dots$ then

$$yT = yT_0 - (h_0 - 2)T_1 + x(yT_1 - 2(h_0 - 3)T_2) + \dots,$$

so

$$T = T_0 + \frac{1}{h_0 - 2} xyT_0 + \frac{1}{2(h_0 - 2)(h_0 - 3)} x^2y^2T_0 + \dots.$$

All order solution given by *solution generating operator*

$$T = :K(z): T_0$$

with

$$K(z) = z^{\frac{h_0-1}{2}} \Gamma(2 - h_0) J_{1-h_0}(2\sqrt{z}) = 1 + \frac{1}{h_0-2}z + \frac{1}{2(h_0-2)(h_0-3)}z^2 + \dots$$

and $z = xy$ with normal ordering

$$:z^k: = x^k y^k.$$

Tangential Operators

We call a bulk operator \mathcal{O} *tangential* if

$$\mathcal{O}\sigma = \sigma\mathcal{O}', \quad \text{for some } \mathcal{O}'$$

Example

- The tangential derivative $\nabla^T := \nabla - n\nabla_n$
- The solution generating operator $:K:$ obeys
 $:K: x = 0$

for same reason that $y:K: = 0$.

- The *holographic GJMS operator*

$$y^k, \quad k \in 2\mathbb{N}$$

acting on tractors with weight $h_0 = k + 1$, because
 $[x, y^k] = y^{k-1}k(h - k + 1)$.

When bulk operators are tangential they define boundary operators since $\mathcal{O}T|_{\Sigma}$ is independent of how T_{Σ} is extended to T .

Obstructions and Anomalies

When $h_0 = 2, 3, \dots$, so $w + \frac{d}{2} = 1, \frac{3}{2}, 2, \dots$, the recurrence

$$T_k = \frac{1}{k(h_0 - k - 1)} y T_{k-1} \quad \text{fails for } T_{h_0-1}.$$

N.B., usually $T_k \sim y^k T_0$, so the operator y^k is the obstruction.

- For conformally Einstein bulk and $h_0 = 2, 4, 6, \dots$, y^k vanishes.
- For $h_0 = 3, 5, 7, \dots$ the tangential operator y^k is a holographic formula for the GJMS operator

$$P_{2k} = \Delta^k + \text{curvatures}.$$

Conformally invariant boundary operators corresponding to conformal anomalies.

- Acting on **log densities**¹ y^{d-1} yields Branson's Q -curvature

$$Q = \frac{1}{((d-2)!!)^2} y^{d-1} U|_{\Sigma}.$$

Holographic anomalies of Henningson–Skenderis.

¹Under conformal transformations $U \mapsto U + \log \Omega$.

Log solutions

Using $[y, x^k] = -x^{k-1}k(h+k-1)$ we learn

$$y: K(z): = : \left(zK''(z) + K'(z)(2-h) + K(z) \right) : y,$$

Operator problem now an ODE—Bessel type-equation solvable by Frobenius method:

- Second solution = z^{h_0-1} (first solution $h_0 \rightarrow 2 - h_0$)
- $h_0 \in \mathbb{N}$, Log solution = (degree $h_0 - 2$ polynomial) + $z^{h_0-1} \log z \times$ (second solution) + “finite terms”
- Log solution requires second scale τ , at definite weight only $\log(\sigma/\tau)$ can appear. $\tau|\Sigma \neq 0$
- $\log z$ is completely formal because $z = xy$, but $\log \tau$ can play rôle of “ $\log y$ ”.
- Algebra of $\log x$,

$$[y, \log x] = -\frac{1}{x}(h-1)$$

- Must also require solution generating operator to be tangential.

The Solution

Remarkably, can solve to all orders at log weights

$$T = \mathcal{O}T_0, \quad \text{solves } l \cdot D T = 0$$

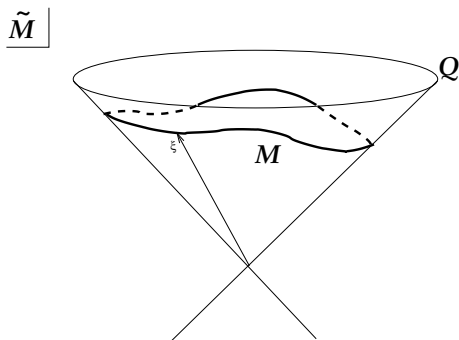
$$\mathcal{O} = :F_{h_0-2}(z): - \frac{:z^{h_0} B(z):}{(h_0-1)!(h_0-2)!} - \frac{x^{h_0-1} \log x :K_{h_0}(z): y^{h_0-1} - x^{h_0-1} :K_{h_0}(z): [\log \tau y^{h_0-1}]_W}{(h_0-1)!(h_0-2)!}$$

- $F_{h_0-2=1+\dots}$ is the standard solution up to orders before obstruction—“infinities”.
- log terms multiply second solution $K_{h_0} = 1+\dots$
- careful Weyl ordering of operators y and $\log \tau$ ensures tangentiality $\mathcal{O}_X = 0$.
- $B = 1+\dots$ are non-log finite terms. **Explicit formulae for all terms.**

Solution of wave equation boundary problem for arbitrary tensors in *any* curved bulk.

Ambient Tractors

Flat model for conformal manifold



- Ambient space $\tilde{M} = \mathbb{R}^{d+1,1}$
- Lightcone $Q = \{X^M X_M = 0\}$
- Conformal manifold $M = \{\text{lightlike rays}\}$

Momentum Cone

Tractors are equivalence classes of weighted ambient tensors T (Gover, Peterson, Čap)

$$T \sim T + X^2 S, \quad X^M \nabla_M T = w T.$$

Tractor operators respect equivalence classes

$$\mathcal{O} X^2 = X^2 \mathcal{O}'$$

Fundamental operators \leftrightarrow momentum space representation of the ambient conformal group (Gover, AW)

Canonical Tractor	X^M
Weight	$w = \nabla_X$
Double D -operator	$D_{MN} = X_N \nabla_M - X_M \nabla_N$
Thomas D -operator	$D_M = \nabla_M (d + 2 \nabla_X - 2) - X_M \Delta$

Curved Cone

Metric on curved ambient space (\tilde{M}, g_{MN}) :

$$g_{MN} = \nabla_M X_N$$

where X is now **hypersurface orthogonal homothetic** vector field.

Consequences:

$$\mathcal{L}_X g_{MN} = 2g_{MN}, \quad \nabla_{[M} X_{N]} = 0, \quad X_M = \nabla_M \frac{1}{2} X^2, \quad g_{MN} = \frac{1}{2} \nabla_M \partial_N X^2.$$

So X^2 is **homothetic potential** and defines a **curved cone**.

Define tractors as before \Rightarrow arbitrary curved space.

Remarkably have an $\mathfrak{sl}(2) \cong \mathfrak{sp}(2)$ algebra from operators **(GJMS)**

$$\mathbb{Q} = \left(\begin{array}{cc} X^2 & \nabla_X + \frac{d+2}{2} \\ \nabla_X + \frac{d+2}{2} & \Delta \end{array} \right), \quad [Q_{ij}, Q_{kl}] = \epsilon_{kj} Q_{ik} + (3 \text{ more})$$

Two Times Physics

Itzhak Bars:

$$H \rightarrow Q_{ij}, \quad \mathbb{R}^{d-1,1} \rightarrow \mathbb{R}^{d,2}$$

because *Howe dual pair*

$$\mathfrak{sp}(2) \otimes \mathfrak{so}(d, 2) \subset \mathfrak{sp}(2(d+2))$$

Particle action

$$S = \int dt \left[P_M \dot{X}^M - \lambda^{ij} Q_{ij} \right], \quad \mathbb{Q} = \begin{pmatrix} X^2 & X \cdot P \\ X \cdot P & P^2 \end{pmatrix} \Leftrightarrow \begin{cases} \text{relativistic particle} \\ \text{AdS particle} \\ H\text{-atom} \\ \text{Harmonic Oscillator} \\ \vdots \end{cases}$$

Bars proposed

$$\text{Gravity} \Leftrightarrow \left\{ \begin{array}{l} \text{triplets of Hamiltonians in } 2(d+2) \text{ dimensional phase space} \\ \text{obeying } \mathfrak{sp}(2) \text{ algebra} \end{array} \right\}$$

Confirm this proposal using tractors! (Bonezzi, Latini, AW)

$$\begin{cases} [Q_{ij}, Q_{kl}] = \epsilon_{kj} Q_{il} + \epsilon_{ki} Q_{jl} + \epsilon_{lj} Q_{ik} + \epsilon_{li} Q_{jk} \\ Q\Psi = 0 \end{cases}$$

- Symplectic Gauge Invariance

$$Q \mapsto Q + [Q, \epsilon], \quad \Psi \mapsto \Psi + \epsilon\Psi$$

- Expand Q, ϵ in powers of operator $\nabla \rightarrow$ infinitely many fields
- Solve $\mathfrak{sp}(2)$ conditions

$$Q = \begin{pmatrix} X^M G_{MN} X^M & X^M (\nabla_M + A_M) + \frac{d+2}{2} \\ X^M (\nabla_M + A_M) + \frac{d+2}{2} & (\nabla^M + A^M) G_{MN} (\nabla^N + A^N) \end{pmatrix},$$

$$\epsilon = \alpha + \xi^M (\nabla_M + A_M),$$

with $G_{MN} = \nabla_M X_N$, $X^M F_{MN}(A) = 0$.

Many Actions

- Lagrange multipliers for Hamiltonian constraints

$$S(G_{MN}, A_M, \Psi, \Omega, \Theta, \Lambda) = \int \sqrt{G} \left(\Omega \tilde{\nabla}^2 + \Theta \left[X \cdot \tilde{\nabla} + \frac{d+2}{2} \right] + \Lambda X^2 \right) \Psi$$

- Θ fixes weight $\nabla_X \Psi = (w - \frac{d}{2} - 1) \Psi$
- Λ says $\Psi = \delta(X^2) \phi$ so $\phi \sim \phi + X^2 \chi$
- $\Rightarrow S = \int \sqrt{G} \delta(X^2) T(G, A, \Omega, \phi)$
- $T = \phi (\nabla + A)^2 \Omega$ must be a tractor: in Maxwell gauge $X \cdot A = w$

$$T = \phi \left(\frac{1}{w} A^M D_M - \frac{1}{d-2} (D^M A_M) + A^2 \right) \Omega$$

- T tractor $\Rightarrow d$ -dimensional action $S = \int \sqrt{-g} T$
- Residual $SO(1, 1)$ gauge invariance

$$\delta \Omega = \alpha \Omega, \quad \delta \phi = -\alpha \phi, \quad \delta A^M = \frac{1}{d-2} D^m \alpha$$

- Singlet $\Omega\phi =: \varphi^2$ is gauge invariant.
- Integrate out A_M leaves only φ and metric

$$S = \int \sqrt{-g} \varphi \left[\Delta - \frac{d-2}{2} \mathbf{J} \right] \varphi$$

CONFORMALLY IMPROVED SCALAR

- In terms of scale

$$\varphi = \sigma^{1-\frac{d}{2}}$$

- Tractor Einstein–Hilbert action

$$S = \int \frac{\sqrt{-g}}{\sigma^d} I^2$$

Weyl invariant

- Choose $\sigma = 1$,

$$S = \int \sqrt{-g} R.$$

Conclusions and Outlook



- Transversal tensors.
- Ubiquity of $I \cdot D$, harmonic Weyl tensor $\rightarrow I \cdot \not{D} W_{MNRS} = 0$ for Weyl tractor.
- Global solution?
- Correlator calculus.
- Two times and dualities.